RM OFFFLINE

Week-1

# Arduino

* Worked with basic Arduino components including ultrasonic sensor, IR sensor, dc motors, led etc.

# LSA08

* Learnt about LSA08 sensor which is a line following sensor

# MDD10A/MD30C

* Learnt how to use motor drivers along with a dc motor

# Holonomic Drive

* Learnt about holonomic driver, how we can use 4 wheels for making the robot move in all directions without rotating it.